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THE EXISTENCE OF PATH-FACTOR COVERED GRAPHS

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Abstract

A spanning subgraph H of a graph G is called a $P_{\geq k}$ -factor of G if every component of H is isomorphic to a path of order at least k, where $k \geq 2$. A graph G is called a $P_{\geq k}$ -factor covered graph if there is a $P_{\geq k}$ -factor of G covering e for any $e \in E(G)$. In this paper, we obtain two special classes of $P_{\geq 2}$ -factor covered graphs. We also obtain two special classes of $P_{\geq 3}$ -factor covered graphs. Furthermore, it is shown that these results are all sharp.

Keywords: path-factor, $P_{\geq 2}$ -factor covered graph, $P_{\geq 3}$ -factor covered graph, claw-free graph, isolated toughness.

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1. Introduction

We consider only finite simple graph, unless explicitly stated. We refer to [6] for the notation and terminologies not defined here. Let G = (V(G), E(G)) be a simple graph, where V(G) and E(G) denote the vertex set and the edge set of G, respectively. A subgraph H of G is called a spanning subgraph of G if V(H) = V(G) and $E(H) \subseteq E(G)$. A subgraph H of G is called an induced subgraph of G if every pair of vertices in H which are adjacent in G are also adjacent in G. For G is the edgree of G is denoted by G is a graph G is said to be claw-free if there is no induced subgraph of G isomorphic to G.

For a family of connected graphs \mathcal{F} , a spanning subgraph H of a graph G is called an \mathcal{F} -factor of G if each component of H is isomorphic to some graph in \mathcal{F} . A spanning subgraph H of a graph G is called a $P_{\geq k}$ -factor of G if every component of H is isomorphic to a path of order at least k. For example, a $P_{\geq 3}$ -factor means a graph factor in which every component is a path of order at least

three. A graph G is called a $P_{\geq k}$ -factor covered graph if there is a $P_{\geq k}$ -factor of G covering e for any $e \in E(G)$.

Since Tutte proposed the well known Tutte 1-factor theorem [15], there are many results on graph factors [2,3,8,9,16] and $P_{\geq k}$ -factors in claw-free graphs and cubic graphs [4,12,13]. More results on graph factors can be found in the survey papers and books in [2,14,18]. We use $\omega(G)$, i(G) to denote the number of components and isolated vertices of a graph G, respectively. For a subset $X \subseteq V(G)$, G-X denotes the graph obtained from G by deleting all the vertices of X. Akiyama, Avis and Era [1] proved the following theorem, which is a criterion for a graph to have a $P_{\geq 2}$ -factor.

Theorem 1 (Akiyama et al. [2]). A graph G has a $P_{\geq 2}$ -factor if and only if $i(G-X) \leq 2|X|$ for all $X \subseteq V(G)$.

Kaneko [10] introduced the concept of a sun and gave a characterization for a graph with a $P_{\geq 3}$ -factor. It is perhaps the first characterization of graphs which have a path factor not including P_2 . Recently, Kano *et al.* [11] presented a simpler proof for Kaneko's theorem [10].

A graph H is called factor-critical if $H-\{v\}$ has a 1-factor for each $v \in V(H)$. Let H be a factor-critical graph and $V(H) = \{v_1, v_2, \ldots, v_n\}$. By adding new vertices $\{u_1, u_2, \ldots, u_n\}$ together with new edges $\{v_i u_i : 1 \leq i \leq n\}$ to H, the resulting graph is called a sun. Note that, according to Kaneko [10], we regard K_1 and K_2 also as a sun, respectively. Usually, the suns other than K_1 are called big suns. It is called a sun component of G-X if the component of G-X is isomorphic to a sun. We denote by sun(G-X) the number of sun components in G-X.

Theorem 2 (Kaneko [10]). A graph G has a $P_{\geq 3}$ -factor if and only if $sun(G - X) \leq 2|X|$ for all $X \subseteq V(G)$.

Zhang and Zhou [19] proposed the concept of path-factor covered graph, which is a generalization of matching cover. They also obtained a characterization for $P_{\geq 2}$ -factor and $P_{\geq 3}$ -factor covered graphs, respectively.

Theorem 3 (Zhang et al. [19]). Let G be a connected graph. Then G is a $P_{\geq 2}$ -factor covered graph if and only if $i(G-S) \leq 2|S| - \varepsilon(S)$ for all $S \subseteq V(G)$, where $\varepsilon(S)$ is defined by

$$\varepsilon(S) = \begin{cases} 2 & \text{if } S \neq \emptyset \text{ and } S \text{ is not an independent set,} \\ 1 & \text{if } S \neq \emptyset, \text{ } S \text{ is an independent set and there exists} \\ & \text{a component of } G - S \text{ with at least two vertices,} \\ 0 & \text{otherwise.} \end{cases}$$

Theorem 4 (Zhang et al. [19]). Let G be a connected graph. Then G is a $P_{\geq 3}$ -factor covered graph if and only if $sun(G - S) \leq 2|S| - \varepsilon(S)$ for all $S \subseteq V(G)$, where $\varepsilon(S)$ is defined by

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For a connected graph G, its toughness, denoted by t(G), was first introduced by Chvátal [7] as follows. If G is complete, then $t(G) = +\infty$; otherwise,

$$t(G) = \min \left\{ \frac{|S|}{\omega(G-S)} : S \subseteq V(G), \, \omega(G-S) \ge 2 \right\}.$$

Bazgan, Benhamdine, Li and Woźniak [5] showed a toughness condition for the existence of a $P_{\geq 3}$ -factor in a graph.

Theorem 5 (Bazgan, Benhamdine, Li and Woźniak [5]). Let G be a graph with at least three vertices. If $t(G) \ge 1$, then G includes a $P_{>3}$ -factor.

For a connected graph G, its isolated toughness, denoted by I(G), was first introduced by Yang, Ma and Liu [17] as follows. If G is complete, then $I(G) = +\infty$; otherwise,

$$I(G) = \min \left\{ \frac{|S|}{i(G-S)} : S \subseteq V(G), i(G-S) \ge 2 \right\}.$$

Recently, Zhou and Wu [20] obtained three classes of $P_{\geq 3}$ -factor covered graphs.

Theorem 6 (Zhou and Wu [20]). A graph G is a $P_{\geq 3}$ -factor covered graph if one the following holds.

- (i) G is a connected graph with at least three vertices and t(G) > 2/3;
- (ii) G is a connected graph with at least three vertices and I(G) > 5/3;
- (iii) G is a k-regular graph with $k \geq 2$.

In this paper, we proceed to investigate $P_{\geq k}$ -factor covered graphs. We respectively obtain two special classes of $P_{\geq 2}$ -factor covered graphs and $P_{\geq 3}$ -factor covered graphs. Our main results will be shown in Sections 2 and 3, respectively.

2. $P_{\geq 2}$ -Factor Covered Graphs

In this section, we mainly obtain two special classes of $P_{\geq 2}$ -factor covered graphs. First, we will give a sufficient condition for a connected claw-free graph to be a $P_{\geq 2}$ -factor covered graph as following. Note that the result in Theorem 7 is sharp in the sense that there exists a connected claw-free graph of minimum degree 1, which is not a $P_{\geq 2}$ -factor covered graph. An example can be seen in Figure 1.

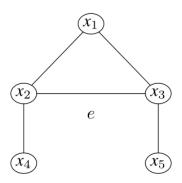


Figure 1. A connected claw-free graph of minimum degree 1 that does not contain any $P_{\geq 2}$ -factor covering $e = x_2x_3$.

Theorem 7. Let G be a connected claw-free graph of minimum degree at least 2. Then G is a $P_{\geq 2}$ -factor covered graph.

Proof. Suppose G is not a $P_{\geq 2}$ -factor covered graph. Then by Theorem 3, there exists a subset $S \subseteq V(G)$ such that $i(G-S) > 2|S| - \varepsilon(S)$. In terms of the integrality of i(G-S), we obtain that $i(G-S) \geq 2|S| - \varepsilon(S) + 1$. We will distinguish two cases below to show that G is a $P_{\geq 2}$ -factor covered graph.

Case 1. $|S| \leq 1$. If $S = \emptyset$, then $\varepsilon(S) = |S| = 0$ by the definition of $\varepsilon(S)$. It follows easily that

$$i(G) = i(G - S) \ge 2|S| - \varepsilon(S) + 1 = 1.$$

On the other hand, $i(G) \leq \omega(G) = 1$ since G is a connected graph. Combining the results above, we obtain i(G) = 1, which contradicts the connectivity of G.

If |S| = 1, let $S = \{s\}$. We obtain $\varepsilon(S) \leq 1$ by the definition of $\varepsilon(S)$. If $\varepsilon(S) = 0$, then

$$\omega(G-S) \ge i(G-S) \ge 2|S| - \varepsilon(S) + 1 = 3.$$

Therefore, if either $\varepsilon(S)$ is 0 or 1, then there are at least three components of $G - \{s\}$. It follows easily that there exists a claw with center vertex s in G, a contradiction.

Case 2. $|S| \ge 2$. Let $|S| = k \ge 2$ and $S = \{s_1, s_2, \dots, s_k\}$. By the definition of $\varepsilon(S)$, we have $\varepsilon(S) \le 2$. It follows easily that

$$i(G - S) \ge 2|S| - \varepsilon(S) + 1 = 2|S| - 1.$$

Let $i(G-S)=m \geq 2k-1$ and $\{x_1,x_2,\ldots,x_m\}$ be the set of isolated vertices of G-S. Since the minimum degree of G is at least two, we immediately obtain the number of edges incident with the vertices in $\{x_1,x_2,\ldots,x_m\}$ is at least 2m. Because G does not have multiple edges and

$$\frac{2m}{|S|} = \frac{2m}{k} \ge \frac{2(2k-1)}{k} = 4 - \frac{2}{k} \ge 3,$$

there must exist a vertex $s_i \in S$ adjacent to at least three vertices in $\{x_1, x_2, \ldots, x_m\}$ by pigeonhole principle. It follows easily that there exists a claw with center vertex s_i in G, a contradiction.

Combining Case 1 and Case 2, Theorem 7 is proved.

Next, we study the relationship between isolated toughness and $P_{\geq 2}$ -factor covered graphs, and obtain an isolated toughness condition for the existence of $P_{\geq 2}$ -factor covered graphs. The example in Figure 2 shows the sharpness of the results in Theorem 8 in the sense that there exists a connected graph with I(G)=2/3, which is not a $P_{\geq 2}$ -factor covered graph.

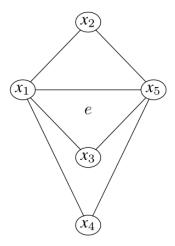


Figure 2. A connected graph with I(G) = 2/3 that does not contain any $P_{\geq 2}$ -factor covering $e = x_1 x_5$.

Theorem 8. Let G be a connected graph with at least two vertices. If I(G) > 2/3, then G is a $P_{\geq 2}$ -factor covered graph.

Proof. If G is a complete graph with at least two vertices, obviously G is a $P_{\geq 2}$ -factor covered graph. Thus we may assume that G is a connected graph with at least two vertices and not complete. Suppose G is not a $P_{\geq 2}$ -factor covered graph. Then by Theorem 3, there exists a subset $S \subseteq V(G)$ such that $i(G-S) > 2|S| - \varepsilon(S)$. Then, by the integrality of i(G-S), we obtain that $i(G-S) \geq 2|S| - \varepsilon(S) + 1$.

Case 1. $|S| \le 1$. If |S| = 0, by the definition of $\varepsilon(S)$, we have $S = \emptyset$ and $\varepsilon(S) = 0$. It follows immediately that

$$i(G) = i(G - S) \ge 2|S| - \varepsilon(S) + 1 = 1,$$

which contradicts the connectivity of G.

Thus we may assume |S|=1, we have $\varepsilon(S)\leq 1$ by the definition of $\varepsilon(S)$. It follows easily that

$$i(G - S) \ge 2|S| - \varepsilon(S) + 1 \ge 2|S|.$$

By the definition of I(G), we have that

$$I(G) \le \frac{|S|}{i(G-S)} \le \frac{1}{2},$$

which contradicts I(G) > 2/3.

Case 2. $|S| \geq 2$. In this case, it follows from the definition of $\varepsilon(S)$ that $\varepsilon(S) \leq 2$, which implies that

$$i(G - S) \ge 2|S| - \varepsilon(S) + 1 \ge 2|S| - 1 \ge 3.$$

Thus we immediately obtain

$$|S| \le \frac{i(G-S)+1}{2}.$$

By the definition of I(G), we have

$$I(G) \le \frac{|S|}{i(G-S)} \le \frac{i(G-S)+1}{2i(G-S)} \le \frac{1}{2} + \frac{1}{2i(G-S)} \le \frac{1}{2} + \frac{1}{6} = \frac{2}{3},$$

which contradicts I(G) > 2/3.

This completes the proof of Theorem 8.

3. $P_{>3}$ -Factor Covered Graphs

In this section, we mainly obtain two special classes of $P_{\geq 3}$ -factor covered graphs. First, we give a minimum degree condition for a connected claw-free graph to be

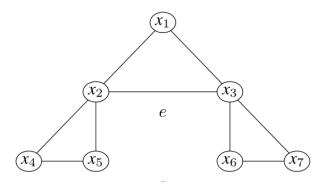


Figure 3. A connected claw-free graph of minimum degree 2 that does not contain any $P_{>3}$ -factor covering $e = x_2x_3$.

a $P_{\geq 3}$ -factor covered graph as following. Note that the results in Theorem 9 is also sharp in the sense that there exists a connected claw-free graph of minimum degree 2, which is not a $P_{\geq 3}$ -factor covered graph. It is shown by the example in Figure 3.

Theorem 9. Let G be a connected claw-free graph of minimum degree at least 3. Then G is a $P_{>3}$ -factor covered graph.

Proof. Suppose G is not a $P_{\geq 3}$ -factor covered graph. Then by Theorem 4, there exists a subset $S \subseteq V(G)$ such that $sun(G-S) > 2|S| - \varepsilon(S)$. In terms of the integrality of sun(G-S), we obtain that $sun(G-S) \geq 2|S| - \varepsilon(S) + 1$. We will distinguish two cases below to show that G is a $P_{\geq 3}$ -factor covered graph.

Case 1. $|S| \leq 1$. If $S = \emptyset$, then $\varepsilon(S) = |S| = 0$ by the definition of $\varepsilon(S)$. It follows easily that

$$sun(G) = sun(G - S) \ge 2|S| - \varepsilon(S) + 1 = 1.$$

On the other hand, $sun(G) \leq \omega(G) = 1$ since G is a connected graph. Combining the results above, we obtain that G is a big sun, which contradicts the minimum degree of G.

If |S| = 1, let $S = \{s\}$. We obtain $\varepsilon(S) \le 1$ by the definition of $\varepsilon(S)$. If $\varepsilon(S) = 0$, then

$$\omega(G-S) \ge sun(G-S) \ge 2|S| - \varepsilon(S) + 1 = 3.$$

Otherwise $\varepsilon(S) = 1$, then there exists a non-sun component of G - S and thus

$$\omega(G-S) > sun(G-S) + 1 > 2|S| - \varepsilon(S) + 1 + 1 = 3.$$

Therefore, if either $\varepsilon(S)$ is 0 or 1, then there are at least three components of $G - \{s\}$. It follows easily that there exists a claw with center vertex s in G, a contradiction.

This completes the proof of Case 1.

Case 2. $|S| \ge 2$. Let $|S| = k \ge 2$ and $S = \{s_1, s_2, \ldots, s_k\}$. By the definition of $\varepsilon(S)$, we have $\varepsilon(S) \le 2$. It follows easily that

$$sun(G-S) \ge 2|S| - \varepsilon(S) + 1 \ge 2|S| - 1.$$

Let $sun(G-S)=m\geq 2k-1$ and $\{C_1,C_2,\ldots,C_m\}$ be the set of sun components of G-S. For any sun component C_i of G-S, let $L(C_i)\subseteq V(C_i)$ be the set of vertices with exactly one neighbour vertex in C_i , and $L(C_i)=V(C_i)$ if $C_i\cong K_1$, where $1\leq i\leq m$. Let $E(S,V(C_i)\setminus L(C_i))$ be the set of edges in graph G between vertex G and G for any G for any G between vertex G and G for any G for any G by deleting all edges of

$$E(G[S]) \cup \left(\bigcup_{i=1}^{m} E(S, V(C_i) \setminus L(C_i))\right)$$

and all vertices of

$$V(G) \setminus S \cup \left(\bigcup_{i=1}^{m} V(C_i)\right)$$

and contracting each C_i to a vertex c_i for $1 \le i \le m$.

Claim 1. For any vertex $u, v \in V(H)$, there are at most two edges between u and v in H.

Proof. Without loss of generality, we assume $u = s_1$ and $v = c_1$. Suppose there are three edges between u and v in H. Then there are three vertices in $L(C_1)$ corresponding to the vertex c_1 , denoted by $\{c_1^1, c_1^2, c_1^3\}$. By the definition of big sun, $c_1^i c_1^j \notin E(G)$ for any $1 \le i < j \le 3$, which implies a claw with center vertex u in G. This is a contradiction.

Since the minimum degree of G is at least three, it is clear that $d_H(c_i) \geq 3$ for $1 \leq i \leq m$. Trivially,

$$|E(H)| \ge 3m \ge 3(2k-1) = 6k - 3.$$

By pigeonhole principle and

$$\frac{|E(H)|}{|S|} \ge \frac{3m}{k} \ge \frac{6k-3}{k} = 6 - \frac{3}{k} > 4,$$

there must exist a vertex $s_i \in S$ incident with at least five edges in E(H). According to Claim 1 and pigeonhole principle, there exists at least three vertices, denoted by $\{c_1, c_2, c_3\}$, adjacent to s_i . Since $\{s_i, c_1, c_2, c_3\}$ induces a claw in H, it follows easily that there exists a claw with center vertex s_i in G, a contradiction. This completes the proof of Case 2.

Combining Case 1 and Case 2, Theorem 9 is proved.

Next, we investigate the relationship between planar graphs and $P_{\geq 3}$ -factor covered graphs, and obtain a connectivity condition for a planar graph to be a $P_{\geq 3}$ -factor covered graphs as following. The example in Figure 4 shows the sharpness of the results in Theorem 11 in the sense that there exists a 2-connected planar graph, which is not a $P_{\geq 3}$ -factor covered graph.

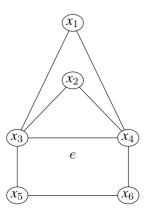


Figure 4. A 2-connected planar graph that does not contain any $P_{\geq 3}$ -factor covering $e = x_3x_4$.

Lemma 10 [6]. Let G be a connected planar graph with at least three vertices. If G does not contain triangles, then $|E(G)| \leq 2|G| - 4$.

Theorem 11. Let G be a 3-connected planar graph. Then G is a $P_{\geq 3}$ -factor covered graph.

Proof. Suppose G is not a $P_{\geq 3}$ -factor covered graph. By Theorem 4, there exists a subset $S \subseteq V(G)$ such that $sun(G-S) > 2|S| - \varepsilon(S)$. According to the integrality of sun(G-S), we obtain that $sun(G-S) \geq 2|S| - \varepsilon(S) + 1$. We distinguish three cases below to show that G is a $P_{\geq 3}$ -factor covered graph.

Case 1. |S| = 0. In this case, by the definition of $\varepsilon(S)$, we have $S = \emptyset$ and $\varepsilon(S) = 0$. Since G is a connected graph, $sun(G) \le \omega(G) = 1$. On the other hand, we obtain that

$$sun(G) = sun(G - S) \ge 2|S| - \varepsilon(S) + 1 = 1.$$

It follows easily that sun(G) = 1, which is to say G is a big sun. By the definition of sun, it contradicts the fact that G is 3-connected. This completes the proof of Case 1.

Case 2. |S| = 1. In this case, we obtain $\varepsilon(S) \leq 1$ by the definition of $\varepsilon(S)$. It follows immediately that

$$sun(G - S) \ge 2|S| - \varepsilon(S) + 1 \ge 2.$$

Let $S = \{x\} \subseteq V(G)$. Since $\omega(G - S) \ge sun(G - S) \ge 2$, x is a cut-vertex of G, which contradicts the fact that G is 3-connected. This completes the proof of Case 2.

Case 3. $|S| \geq 2$. In this case, we obtain $\varepsilon(S) \leq 2$ by the definition of $\varepsilon(S)$. It follows immediately that

$$sun(G-S) \ge 2|S| - \varepsilon(S) + 1 \ge 2|S| - 1.$$

Set |S| = s. We denote by Sun(G-S) the set of sun components in G-S. Since $sun(G-S) \ge 2|S|-1$, let $C_1, C_2, \ldots, C_{2s-1}$ be 2s-1 distinct sun components where $C_i \in Sun(G-S)$ for any $1 \le i \le 2s-1$. Then we construct a bipartite graph H from G by contracting each C_i to a vertex c_i for $1 \le i \le 2s-1$ and deleting all edges of E(G[S]) and all vertices of

$$V(G) \setminus (S \cup \left(\bigcup_{i=1}^{2s-1} V(C_i)\right)\right).$$

Since G is 3-connected, it is clear that $d_H(c_i) \geq 3$ for $1 \leq i \leq 2s - 1$. Trivially,

$$|H| = s + (2s - 1) = 3s - 1 \ge 5,$$

and

$$|E(H)| \ge 3(2s-1) = 6s - 3.$$

As G is a 3-connected planar graph, it is easy to see that H is also a connected planar graph. According to the fact that a bipartite graph does not contain any odd cycles, Lemma 10 implies that

$$6s - 3 \le |E(H)| \le 2|H| - 4 = 2(3s - 1) - 4 = 6s - 6$$

which is a contradiction. This completes the proof of Case 3.

Combining Cases 1–3, Theorem 11 is proved.

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