# TOTAL ROMAN \{2\}-DOMINATING FUNCTIONS IN GRAPHS 

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#### Abstract

A Roman $\{2\}$-dominating function (R2F) is a function $f: V \rightarrow\{0,1,2\}$ with the property that for every vertex $v \in V$ with $f(v)=0$ there is a neighbor $u$ of $v$ with $f(u)=2$, or there are two neighbors $x, y$ of $v$ with $f(x)=f(y)=1$. A total Roman \{2\}-dominating function (TR2DF) is an R2F $f$ such that the set of vertices with $f(v)>0$ induce a subgraph with no isolated vertices. The weight of a TR2DF is the sum of its function values over all vertices, and the minimum weight of a TR2DF of $G$ is the total Roman $\{2\}$-domination number $\gamma_{t R 2}(G)$. In this paper, we initiate the study of total Roman $\{2\}$-dominating functions, where properties are established. Moreover, we present various bounds on the total Roman $\{2\}$-domination number. We also show that the decision problem associated with $\gamma_{t R 2}(G)$ is NP-complete for bipartite and chordal graphs. Moreover, we show that it is


possible to compute this parameter in linear time for bounded clique-width graphs (including trees).
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## 1. Introduction

In this paper, $G$ is a simple graph with vertex set $V=V(G)$ and edge set $E=E(G)$. The order $|V|$ of $G$ is denoted by $n(G)$. For every vertex $v \in V$, the open neighborhood $N(v)$ is the set $\{u \in V(G): u v \in E(G)\}$ and the closed neighborhood of $v$ is the set $N[v]=N(v) \cup\{v\}$. The degree of a vertex $v \in V$ is $\operatorname{deg}_{G}(v)=|N(v)|$. The minimum and maximum degree of a graph $G$ are denoted by $\delta=\delta(G)$ and $\Delta=\Delta(G)$, respectively. A leaf of $G$ is a vertex of degree one, while a support vertex of $G$ is a vertex adjacent to a leaf. A support vertex is said to be weak (respectively, strong) if it is adjacent to exactly one leaf (respectively, at least two leaves).

Let $P_{n}, C_{n}$ and $K_{n}$ be the path, cycle and complete graph of order $n$ and $K_{p, q}$ the complete bipartite graph with one partite set of cardinality $p$ and the other of cardinality $q$. The complement of a graph $G$ is denoted by $\bar{G}$. The join of two graphs $G$ and $H$, denoted by $G \vee H$, is a graph obtained from $G$ and $H$ by joining each vertex of $G$ to all vertices of $H$. A tree is an acyclic connected graph. A double star is a tree containing exactly two vertices that are not leaves. A double star with respectively $p$ and $q$ leaves attached at each support vertex is denoted by $S_{p, q}$. The corona of a graph $H$ is the graph obtained from $H$ by appending a vertex of degree 1 to each vertex of $H$. The distance $d_{G}(u, v)$ between two vertices $u$ and $v$ in a connected graph $G$ is the length of a shortest $u-v$ path in $G$. The diameter of $G$, denoted by $\operatorname{diam}(G)$, is the maximum value among distances between all pair of vertices of $G$.

A subset $S \subseteq V$ is a dominating set if every vertex in $V \backslash S$ has a neighbor in $S$, and $S$ is a total dominating set, abbreviated TSD, if every vertex in $V$ has a neighbor in $S$, that is, $N(v) \cap S \neq \emptyset$ for all $v \in V$. The domination number $\gamma(G)$ of a graph $G$ is the minimum cardinality of a dominating set of $G$, and the total domination number $\gamma_{t}(G)$ is the minimum cardinality of a TDS of $G$.

For a graph $G$ and a positive integer $k$, let $f: V(G) \rightarrow\{0,1,2, \ldots, k\}$ be a function, and let $\left(V_{0}, V_{1}, V_{2}, \ldots, V_{k}\right)$ be the ordered partition of $V=V(G)$ induced by $f$, where $V_{i}=\{v \in V: f(v)=i\}$ for $i \in\{0,1, \ldots, k\}$. There is a 1-1 correspondence between the functions $f: V \rightarrow\{0,1,2, \ldots, k\}$ and the ordered partitions $\left(V_{0}, V_{1}, V_{2}, \ldots, V_{k}\right)$ of $V$, so we will write $f=\left(V_{0}, V_{1}, V_{2}, \ldots, V_{k}\right)$. The weight of $f$ is the value $f(V(G))=\sum_{u \in V(G)} f(u)$.

A function $f: V(G) \rightarrow\{0,1,2\}$ is a Roman dominating function, abbreviated RDF, on $G$ if every vertex $u \in V$ for which $f(u)=0$ is adjacent to at least one vertex $v$ for which $f(v)=2$. The Roman domination number $\gamma_{R}(G)$ is the minimum weight of a RDF on $G$. Roman domination was introduced by Cockayne et al. in [4] and was inspired by the work of ReVelle and Rosing [10], and Stewart [11].

The definition of Roman dominating functions was motivated by an article in Scientific American by Stewart entitled "Defend the Roman Empire" [11] and suggested even earlier by ReVelle [9]. Each vertex in our graph represents a location in the Roman Empire. A location (vertex $v$ ) is considered unsecured if no legions are stationed there (i.e., $f(v)=0$ ) and secured otherwise (i.e., if $f(v) \in\{1,2\}$ ). An unsecured location (vertex $v$ ) can be secured by sending a legion to $v$ from a neighboring location (an adjacent vertex $u$ ). But Constantine the Great (Emperor of Rome) issued a decree in the 4th century A.D. for the defense of the regions, where a legion cannot be sent from a secured location having only one legion stationed there to an unsecured location, for otherwise it leaves that location unsecured. Thus, two legions must be stationed at a location $(f(v)=2)$ before one of the legions can be sent to a neighboring location. In this way, Emperor Constantine the Great can defend the Roman Empire. Since it is expensive to maintain a legion at a location, the Emperor would like to station as few legions as possible, while still defending the Roman Empire. A Roman dominating function of weight $\gamma_{R}(G)$ corresponds to such an optimal assignment of legions to locations.

In [2], Chellali et al. introduced the Roman $\{2\}$-domination (called in [7] and elsewhere Italian domination) defined as follows: a Roman $\{2\}$-dominating function is a function $f=\left(V_{0}, V_{1}, V_{2}\right)$ with the property that for every vertex $v \in V_{0}$ there is a vertex $u \in N(v)$, with $u \in V_{2}$ or there are two vertices $x, y \in N(v)$ with $x, y \in V_{1}$. The Roman $\{2\}$-domination number $\gamma_{\{R 2\}}(G)$ is the minimum weight of a Roman $\{2\}$-dominating function on $G$.

There are many papers in the literature devoted to the study of Roman domination type problems and its variations. One of the questions that arise naturally when a Roman domination type problem is studied is to focus on its complexity and algorithmic aspects. In 2008, Liedloff et al. [8] showed, among other results, that it is possible to compute the Roman domination number of a graph with bounded cliquewidth in linear time. Clearly, this implies that there exists algorithms for computing the Roman domination number of trees in linear time. Chellali et al. [2] proved that Roman \{2\}-domination problem is NPcomplete for bipartite graphs while Chen and Lu [3] recently showed it is NPcomplete even when restricted to split graphs. Moreover, the authors [3] presented a linear time algorithm to obtain the Roman $\{2\}$-domination number of a block graph.

In this paper, we initiate the study of the total version of Roman $\{2\}$ dominating function. A total Roman $\{2\}$-dominating function, abbreviated TR2DF, is a Roman $\{2\}$-dominating function $f=\left(V_{0}, V_{1}, V_{2}\right)$ such that the subgraph induced by $V_{1} \cup V_{2}$ has no isolated vertices. The total Roman $\{2\}$-domination number $\gamma_{t R 2}(G)$ is the minimum weight of a TR2DF on $G$. A TR2DF on $G$ with weight $\gamma_{t R 2}(G)$ is called a $\gamma_{t R 2}(G)$-function. Total Roman $\{2\}$-domination number is well-defined for all graphs $G$ with no isolated vertices since assigning a 1 to every vertex of $G$ provides a TR2DF of $G$. Hence for all graphs $G$ of order $n$ with $\delta(G) \geq 1,2 \leq \gamma_{t R 2}(G) \leq n$. We present various bounds on the total Roman $\{2\}$-domination number and several properties are established. We show that the decision problem associated with $\gamma_{t R 2}(G)$ is NP-complete for bipartite and chordal graphs. Moreover, we show that it is possible to compute this parameter in linear time for bounded clique-width graphs (including trees).

We note that throughout this paper, we only consider nontrivial connected graphs that we will call ntc graphs.

## 2. Preliminary Results

We begin by giving some properties of total Roman $\{2\}$-dominating functions. The following two facts lead to our first observation. Clearly assigning a 2 to every vertex in a minimum total dominating set of a ntc graph $G$ and a 0 to the remaining vertices of $G$ provides a TR2DF. Also, for every TR2DF $f=$ $\left(V_{0}, V_{1}, V_{2}\right)$ the set $V_{1} \cup V_{2}$ total dominates $V(G)$.
Observation 1. For every ntc graph $G$,

$$
\gamma_{t}(G) \leq \gamma_{t R 2}(G) \leq 2 \gamma_{t}(G)
$$

Note that the lower bound of Observation 1 is attained for $K_{2} \vee \overline{K_{n-2}}$ while the upper bound is attained for the double star $S_{3,3}$.

It is well-known that $\gamma_{t}(G) \leq 2 \gamma(G)$ for every ntc graph $G$. So by Observation 1, we will have $\gamma_{t R 2}(G) \leq 4 \gamma(G)$. Our next result improves this upper bound to $\gamma_{t R 2}(G) \leq 3 \gamma(G)$. We need the following result due to Bollobás and Cockayne [1]. If $S$ is a set of vertices, then we say that a vertex $v$ is a private neighbor of a vertex $u \in S$ (with respect to $S$ ) if $N[v] \cap S=\{u\}$. The external private neighborhood epn $(u, S)$ of $u$ with respect to $S$ consists of those private neighbors of $u$ in $V \backslash S$. For a TR2DF $f=\left(V_{0}, V_{1}, V_{2}\right)$ of an ntc graph, let $V_{02}=\left\{w \in V_{0}: N(w) \cap V_{2} \neq \emptyset\right\}$ and $V_{01}=V_{0} \backslash V_{02}$.
Theorem 2 (Bollobás and Cockayne [1]). If $G$ is a graph without isolated vertices, then $G$ has a minimum dominating set $D$ such that for all $d \in D$, there exists a neighbor $f(d) \in V \backslash D$ of $d$ such that $f(d)$ is not a neighbor of any vertex $x \in D \backslash\{d\}$.

Proposition 3. For every ntc graph $G, \gamma_{t R 2}(G) \leq 3 \gamma(G)$.
Proof. Let $D$ be a minimum dominating set of $G$ satisfying the property of Theorem 2. Since each vertex of $D$ has an external private neighbor in $V \backslash D$, let $W$ be a subset of $V \backslash D$ formed by the private neighbors chosen so that each vertex of $D$ has exactly one external private neighbor in $D$. Clearly $|W|=|D|$. Now define the function $f$ as follows: $f(x)=2$ for all $x \in D, f(x)=1$ for all $x \in W$, and $f(x)=0$ otherwise. Clearly $f$ is a TR2DF of $G$ of weight $2|D|+|W|=3 \gamma(G)$, and thus $\gamma_{t R 2}(G) \leq 3 \gamma(G)$.

For the sharpness of the bound in Proposition 3, consider the tree $T$ obtained from two stars $K_{1,4}$ by adding an edge between a leaf of one star to a leaf of the other star. The next observation is straightforward and is tight for double stars.

Observation 4. For every ntc graph $G, \gamma_{R 2}(G) \leq \gamma_{t R 2}(G)$.
Proposition 5. Let $G$ be an ntc graph. Then for every $\gamma_{t R 2}(G)$-function $f=\left(V_{0}\right.$, $\left.V_{1}, V_{2}\right)$ such that $\left|V_{2}\right|$ is as small as possible, we have the following.
(i) Each vertex in $V_{2}$ has at least two private neighbors in $V_{0}$ with respect to $V_{2}$.
(ii) $2\left|V_{2}\right| \leq\left|V_{02}\right|$.

Proof. (i) Suppose there exists a vertex $v \in V_{2}$ with at most one private neighbor in $V_{0}$ with respect to $V_{2}$. Then reassigning $v$ and its private neighbor (if any) the value 1 instead of 2 and 0 , respectively provides a $\gamma_{t R 2}(G)$-function with less vertices assigned a 2 , which contradicts the choice of $f$.
(ii) Follows from (i).

Proposition 6. Let $G$ be an ntc graph with maximum degree $\Delta \leq 2$. Then there exists a $\gamma_{t R 2}(G)$-function $f=\left(V_{0}, V_{1}, V_{2}\right)$ such that $V_{2}=\emptyset$.

Proof. Among all $\gamma_{t R 2}(G)$-functions, let $f=\left(V_{0}, V_{1}, V_{2}\right)$ be a one such that $\left|V_{2}\right|$ is as small as possible. If $V_{2} \neq \emptyset$, then by Proposition 5 , every vertex of $V_{2}$ has at least two private neighbors in $V_{0}$ with respect to $V_{2}$. But then since $\Delta \leq 2$, each vertex in $V_{2}$ would be isolated in $G\left[V_{1} \cup V_{2}\right]$, a contradiction. Hence $V_{2}=\emptyset$.

Recall that a subset $S$ of $V$ is a double dominating set of $G$ if for every vertex $v \in V,|N[v] \cap S| \geq 2$, that is, $v$ is in $S$ and has at least one neighbor in $S$ or $v$ is in $V \backslash S$ and has at least two neighbors in $S$. The double domination number $\gamma_{\times 2}(G)$ is the minimum cardinality of a double dominating set of $G$. Double domination was introduced by Harary and Haynes [6] who proved that $\gamma_{\times 2}\left(P_{n}\right)=\left\lceil\frac{2 n+2}{3}\right\rceil$ and $\gamma_{\times 2}\left(C_{n}\right)=\left\lceil\frac{2 n}{3}\right\rceil$. The following result shows that the equality between $\gamma_{t R 2}(G)$ and $\gamma_{\times 2}(G)$ occurs under certain conditions.

Proposition 7. Let $G$ be an ntc graph. If $G$ has a $\gamma_{t R 2}(G)$-function $f=\left(V_{0}\right.$, $\left.V_{1}, V_{2}\right)$ such that $V_{2}=\emptyset$, then $\gamma_{t R 2}(G)=\gamma_{\times 2}(G)$.

Proof. If $S$ is a double dominating set of $G$, then $(V \backslash S, S, \emptyset)$ is clearly a TR2DF on $G$, and thus $\gamma_{t R 2}(G) \leq \gamma_{\times 2}(G)$. Now if $f=\left(V_{0}, V_{1}, V_{2}\right)$ is a $\gamma_{t R 2}(G)$-function such that $V_{2}=\emptyset$, then $V_{1}$ double dominates $V(G)$, and thus $\gamma_{\times 2}(G) \leq \gamma_{t R 2}(G)$. Therefore $\gamma_{t R 2}(G)=\gamma_{\times 2}(G)$.

The following results are immediate consequences of Propositions 6, 7 and the exact values of the double domination number of paths and cycles given above.

Proposition 8. For $n \geq 2, \gamma_{t R 2}\left(P_{n}\right)=\left\lceil\frac{2 n+2}{3}\right\rceil$.
Proposition 9. For $n \geq 3, \gamma_{t R 2}\left(C_{n}\right)=\left\lceil\frac{2 n}{3}\right\rceil$.

## 3. COMPLEXITY

Our aim in this section is to study the complexity of the following decision problem, to which we shall refer as TOTAL ROMAN $\{2\}$-DOMINATION.

## TOTAL ROMAN $\{2\}$-DOMINATION

Instance: Graph $G=(V, E)$, positive integer $k \leq|V|$.
Question: Does $G$ have a total Roman \{2\}-dominating function of weight at most $k$ ?

We show that this problem is NP-complete by reducing the well-known NP-complete problem, Exact-3-Cover (X3C), to TOTAL ROMAN \{2\}-DOMINATION.

## EXACT 3-COVER (X3C)

Instance: A finite set $X$ with $|X|=3 q$ and a collection $C$ of 3-element subsets of $X$.
Question: Is there a subcollection $C^{\prime}$ of $C$ such that every element of $X$ appears in exactly one element of $C^{\prime}$ ?

Theorem 10. TOTAL ROMAN \{2\}-DOMINATION is NP-Complete for bipartite graphs.

Proof. TOTAL ROMAN $\{2\}-D O M I N A T I O N$ is a member of $\mathcal{N} \mathcal{P}$, since we can check in polynomial time that a function $f: V \rightarrow\{0,1,2\}$ has weight at most $k$ and is a total Roman $\{2\}$-dominating function. Now let us show how to transform any instance of X3C into an instance $G$ of TOTAL ROMAN $\{2\}$-DOMINATION so that one of them has a solution if and only if the other one has a solution. Let $X=\left\{x_{1}, x_{2}, \ldots, x_{3 q}\right\}$ and $C=\left\{C_{1}, C_{2}, \ldots, C_{t}\right\}$ be an arbitrary instance of X3C.

For each $x_{i} \in X$, we build a graph $H_{i}$ obtained from a path $P_{2}: x_{i}-y_{i}$ and two stars $K_{1,3}$ centered at $a_{i}$ and $b_{i}$, by adding edges $y_{i} a_{i}$ and $y_{i} b_{i}$. Hence, each $H_{i}$


Figure 1. NP-Completeness for bipartite graphs.
has order 10. For each $C_{j} \in C$, we build a double star $S_{3,3}$ with support vertices $u_{j}$ and $v_{j}$. Let $c_{j}$ be a leaf of the double star $S_{3,3}$. Let $Y=\left\{c_{1}, c_{2}, \ldots, c_{t}\right\}$. Now to obtain a graph $G$, we add edges $c_{j} x_{i}$ if $x_{i} \in C_{j}$. Clearly $G$ is a bipartite graph. Set $k=4 t+16 q$. Observe that for every total Roman $\{2\}$-dominating function $f$ on $G$, each $H_{i}$ has weight at least 5 and each double star $S_{3,3}$ has weight at least 4.

Suppose that the instance $X, C$ of X3C has a solution $C^{\prime}$. We construct a total Roman $\{2\}$-dominating function $f$ on $G$ of weight $k$. For each $i$, assign the value 2 to $a_{i}, b_{i}$; the value 1 to $y_{i}$ and 0 to the remaining vertices of $H_{i}$. For every $j$, assign the value 2 to $u_{j}$ and $v_{j}$, and 0 to each leaf. In addition, for every $c_{j}$, assign the value 1 if $C_{j} \in C^{\prime}$ and the value 0 if $C_{j} \notin C^{\prime}$. Note that since $C^{\prime}$ exists, its cardinality is precisely $q$, and so the number of $c_{j}$ 's with value 1 is $q$, having disjoint neighborhoods in $\left\{x_{1}, x_{2}, \ldots, x_{3 q}\right\}$. Since $C^{\prime}$ is a solution for X3C, every vertex in $X$ is adjacent to two vertices assigned a 1. Hence, it is straightforward to see that $f$ is a total Roman $\{2\}$-dominating function with weight $f(V)=4 t+q+15 q=k$.

Conversely, suppose that $G$ has a total Roman $\{2\}$-dominating function with weight at most $k$. Among all such functions, let $g=\left(V_{0}, V_{1}, V_{2}\right)$ be one such that $\left\{y_{1}, y_{2}, \ldots, y_{3 q}\right\} \cap V_{2}$ is as small as possible. As observed above, since each $H_{i}$ has weight at least 5 , we may assume that $g\left(a_{i}\right)=g\left(b_{i}\right)=2$ and $g\left(y_{i}\right)>0$ so that vertices $a_{i}, b_{i}$ are not isolated in the subgraph induced by $V_{1} \cup V_{2}$. Hence each leaf neighbor of $a_{i}$ or $b_{i}$ is assigned a 0 under $g$. If $g\left(y_{i}\right)=2$ for some $i$, then we must have $g\left(x_{i}\right)=0$. In this case, reassigning a 1 to each of $y_{i}$ and $x_{i}$ instead of 2 and 0 , respectively, provides a total Roman $\{2\}$-dominating function $g^{\prime}$ with less vertices $y_{i}$ assigned a 2 than under $g$, contradicting our choice of $g$. Hence $g\left(y_{i}\right)=1$ for every $i \in\{1,2, \ldots, 3 q\}$. On the other hand, the total weight
of all double stars corresponding to elements of $C$ is at least $4 t$. In this case, we can assume that $g\left(u_{j}\right)=g\left(v_{j}\right)=2$ and so each leaf neighbor of $u_{j}$ or $b_{j}$ is assigned a 0 under $g$. Note that each $c_{j}$ can be assigned a 0 since $g\left(u_{j}\right)=2$. Since $w(g) \leq 4 t+16 q$ and the total weight assigned to vertices of $V(G) \backslash(X \cup Y)$ is $4 t+15 q$, we have to assign to vertices of $(X \cup Y)$ weights whose total not exceeding $q$ in order that each vertex $x_{i} \in X$ has either $g\left(x_{i}\right)>0$ or has two neighbors in $V_{1}$. Since $|X|=3 q$, it is clear that this is only possible if there are $q$ vertices of $\left\{c_{1}, c_{2}, \ldots, c_{t}\right\}$ that are assigned a 1 . Since each $c_{j}$ has a exactly three neighbors in $\left\{x_{1}, x_{2}, \ldots, x_{3 q}\right\}$, we deduce that $C^{\prime}=\left\{C_{j}: g\left(c_{j}\right)=1\right\}$ is an exact cover for $C$.

The next result is obtained by using the same proof of Theorem 10 on the (same) graph $G$ built for the transformation by adding all edges between the vertices labelled $c_{j}$ in order that the resulting graph is chordal.

Theorem 11. TOTAL ROMAN $\{2\}$-DOMINATION is NP-Complete for chordal graphs.

In the rest of this section, we prove that the decision problem associated to $\gamma_{t R 2}(G)$ can be solved in linear time for the class of graphs with bounded clique-width, which implies that it also can be computed in linear time for trees.

We make use of several useful objects and results, which are formally described in $[5,8]$, related to logic structures. Namely, in what follows, a $k$ expression on the vertices of a graph $G$ with labels $\{1,2, \ldots, k\}$ is an expression using the following operations.

- $i(x)$ create a new vertex $x$ with label $i$,
$G_{1} \oplus G_{2}$ create a new graph which is the disjoint union of the graphs $G_{i}$,
$\eta_{i j}(G)$ add all edges in $G$ joining vertices with label $i$ with vertices with label $j$, $\rho_{i \rightarrow j}(G)$ change the label of all vertices with label $i$ into label $j$.
We call the clique-width of a graph $G$ the minimum positive integer $k$ that is needed to describe $G$ by means of a $k$-expression. For example, the complete graph $K_{3}$ with set of vertices $\{a, b, c\}$ can be described by the following 2-expression.

$$
\rho_{2 \rightarrow 1}\left(\eta_{12}\left(\rho_{2 \rightarrow 1}\left(\eta_{12}(\bullet 1(a) \oplus \bullet 2(b))\right) \oplus \bullet 2(c)\right)\right) .
$$

In what follows, $\operatorname{MSOL}\left(\tau_{1}\right)$ stands for the monadic second order logic with quantification over subsets of vertices. We denote by $G\left(\tau_{1}\right)$ the logic structure $<$ $V(G), R>$ where $R$ is a binary relation such that $R(u, v)$ holds if and only if $u v$ is an edge in $G$. An optimization problem is a $\operatorname{LinEMSOL}(\tau)$ optimization problem if it can be described in the following way (see [8] for more details, since this is a version of the definition given by [5] restricted to finite simple graphs),

$$
O p t\left\{\sum_{1 \leq i \leq l} a_{i}\left|X_{i}\right|:<G\left(\tau_{1}\right), X_{1}, \ldots, X_{l}>\vDash \theta\left(X_{1}, \ldots, X_{l}\right)\right\}
$$

where $\theta$ is an $\operatorname{MSOL}\left(\tau_{1}\right)$ formula that contains free set-variables $X_{1}, \ldots, X_{l}$, integers $a_{i}$ and $O p t$ is either min or max.

We use the following result on LinEMSOL optimization problems.
Theorem 12 (Courcelle et al. [5]). Let $k \in \mathbb{N}$ and let $\mathcal{C}$ be a class of graphs of clique-width at most $k$. Then every LinEMSOL $\left(\tau_{1}\right)$ optimization problem on $\mathcal{C}$ can be solved in linear time if a $k$-expression of the graph is part of the input.

We extend a result proved by Liedloff et al. (see Theorem 31 in [8]) regarding the complexity of the Roman domination decision problem to the corresponding decision problem for the total Roman $\{2\}$-domination number.
Theorem 13. The total Roman $\{2\}$-domination problem is a $\operatorname{LinEMSOL}\left(\tau_{1}\right)$ optimization problem.
Proof. Let us show that the total Roman \{2\}-domination problem can be expressed as a $\operatorname{LinEMSOL}\left(\tau_{1}\right)$ optimization problem. Let $f=\left(V_{0}, V_{1}, V_{2}\right)$ be a total Roman $\{2\}$-domination function in $G=(V, E)$ and let us define the free set-variables $X_{i}$ such that $X_{i}(v)=1$ whenever $v \in V_{i}$ and $X_{i}(v)=0$, otherwise. For the sake of congruence with the logical system notation, we denote by $\left|X_{i}\right|=\sum_{v \in V} X_{i}(v)$, even when, clearly, is $\left|X_{i}\right|=\left|V_{i}\right|$. Observe that the total Roman $\{2\}$-domination decision problem corresponds to achieve the optimum for the following expression.

$$
\min _{X_{i}}\left\{\left|X_{1}\right|+2\left|X_{2}\right|:<G\left(\tau_{1}\right), X_{0}, X_{1}, X_{2}>\vDash \theta\left(X_{0}, X_{1}, X_{2}\right)\right\},
$$

where $\theta$ is the formula given by

$$
\begin{aligned}
\theta\left(X_{0}, X_{1}, X_{2}\right) & =\left(\forall v\left(\left(X_{1}(v) \vee X_{2}(v)\right) \rightarrow \exists u\left(\left(X_{1}(u) \vee X_{2}(u)\right) \wedge R(u, v)\right)\right)\right) \\
& \wedge\left(\forall v \left(X_{1}(v) \vee X_{2}(v) \vee \exists u\left(R(u, v) \wedge X_{2}(u)\right)\right.\right. \\
& \left.\left.\vee \exists u, w\left(R(u, v) \wedge R(w, v) \wedge X_{1}(u) \wedge X_{1}(w)\right)\right)\right) .
\end{aligned}
$$

Clearly, $\theta$ is an $\operatorname{MSOL}\left(\tau_{1}\right)$ formula that describes the total Roman $\{2\}-$ domination problem. Namely, the formula has two main clauses. The first one requires that every vertex $v$ with a positive label 1 or 2 must have a neighbor $u$ with a positive label. The latter implies that the induced subgraph by the set of vertices $V_{1} \cup V_{2}$ has no isolated vertices. The second clause of the formula assures that for any vertex $v$ of the graph either the vertex itself has a positive label, or either it has a neighbor with a label 2 , or either it has two different neighbors having label 1 each. Hence, when the formula $\theta$ is satisfied, the requirements of a total Roman \{2\}-domination assignment in $G$ holds.

As a consequence, we may derive the following corollary.
Corollary 14. The decision problem associated to the total Roman $\{2\}$-domination problem can be solved in linear time on any graph $G$ with clique-width bounded by a constant $k$, provided that either there exists a linear-time algorithm to construct a $k$-expression of $G$, or a $k$-expression of $G$ is part of the input.

Since any graph with bounded treewidth is also a bounded clique-width graph, and it is well-known that any tree graph has treewidth equal to 1 , then we can deduce that the total Roman $\{2\}$-domination problem can be solved in linear time for the class of trees. Besides, there are several classes of graphs $G$ with bounded clique-width $c w(G)$ like, for example, the cographs $(c w(G) \leq 2)$ and the distance hereditary graphs $(c w(G) \leq 3)$, for which it is also possible to solve the total Roman $\{2\}$-domination problem in linear time.

## 4. Graphs with Small or Large Total Roman $\{2\}$-domination

As mentioned in Section 1, for all ntc graphs $G$ of order $n, 2 \leq \gamma_{t R 2}(G) \leq n$. In this section, we characterize all ntc graphs $G$ such that $\gamma_{t R 2}(G) \in\{2,3, n\}$.

Proposition 15. Let $G$ be an ntc graph. For any graph $H$, we have $\gamma_{t R 2}\left(K_{2} \vee\right.$ $H)=2$. Conversely, if $\gamma_{t R 2}(G)=2$, there is some graph $H$ such that $G=K_{2} \vee H$.

Proof. If $G=K_{2} \vee H$, then clearly $\gamma_{t R 2}(G)=2$. Conversely, assume that $\gamma_{t R 2}(G)=2$ and let $f=\left(V_{0}, V_{1}, V_{2}\right)$ be a $\gamma_{t R 2}(G)$-function. By definition of TR2DF of $G$, we have $\gamma_{t R 2}(G)=\left|V_{1}\right|+2\left|V_{2}\right|=2$. Since $G\left[V_{1} \cup V_{2}\right]$ has no isolated vertex, we deduce that $\left|V_{2}\right|=0$ and $\left|V_{1}\right|=2$. Now let $V_{1}=\{x, y\}$. Clearly, $x y \in E(G)$, because $G\left[V_{1} \cup V_{2}\right]$ has no isolated vertex, and every vertex in $V(G) \backslash\{x, y\}$ is adjacent to both $x$ and $y$. Thus $G \cong K_{2} \vee H$, and $H$ is any graph of order $n-2$.

Proposition 16. Let $G$ be an ntc graph of order $n \geq 5$. Then $\gamma_{t R 2}(G)=3$ if and only if either $G$ has exactly one vertex of degree $n-1$ or $\Delta(G) \leq n-2$ and $G$ is obtained from two disjoint graphs $G_{1}$ and $G_{2}$ such that $G_{1} \in\left\{P_{3}, C_{3}\right\}$ and $G_{2}$ is any graph of order $n-3$ by adding edges between vertices of $G_{1}$ and $G_{2}$ in order that every vertex of $G_{2}$ has at least two neighbors in $G_{1}$.

Proof. If $\Delta(G)=n-1$ and $G$ has exactly one vertex $u$ of degree $n-1$, then the function $f$ defined on $V(G)$ by $f(u)=2, f(v)=1$ for some $v \in V(G) \backslash\{u\}$ and $f(w)=0$ for all $w \in V \backslash\{u, v\}$ is a TR2DF and so $\gamma_{t R 2}(G) \leq 3$. Since $G$ has exactly one vertex of degree $n-1$, we deduce from Proposition 15 that $\gamma_{t R 2}(G) \geq 3$ and the equality follows.

Now assume that $\Delta(G) \leq n-2$ and $G$ is obtained from two disjoint graphs $G_{1}$ and $G_{2}$ such that $G_{1} \in\left\{P_{3}, C_{3}\right\}$ and $G_{2}$ is any graph of order $n-3$ by adding edges between vertices of $G_{1}$ and $G_{2}$ in order that every vertex of $G_{2}$ has at least two neighbors in $G_{1}$. Then the function $f$ defined on $V(G)$ by $f(u)=1$ for every vertex $u \in V\left(G_{1}\right)$ and $f(v)=0$ for all $v \in V\left(G_{2}\right)$ is a TR2DF of $G$. Hence $\gamma_{t R 2}(G) \leq 3$, and the equality follows as above from Proposition 15.

Conversely, assume that $\gamma_{t R 2}(G)=3$. Then $G$ has at most one vertex of degree $n-1$, for otherwise $\gamma_{t R 2}(G)=2$ (by Proposition 15). Let $f=\left(V_{0}, V_{1}, V_{2}\right)$ be a $\gamma_{t R 2}(G)$-function. Since $\gamma_{t R 2}(G)=\left|V_{1}\right|+2\left|V_{2}\right|=3$, then it must be either $\left|V_{1}\right|=\left|V_{2}\right|=1$ or either $\left|V_{1}\right|=3$ and $\left|V_{2}\right|=0$. If $\left|V_{1}\right|=\left|V_{2}\right|=1$, with $V_{2}=\{u\}$ and $V_{1}=\{v\}$, then $u v \in E(G)$ and every vertex in $V \backslash\{x, y\}$ must be adjacent to $u$, because $f$ is a TR2DF. So $u$ is the unique vertex of degree $n-1$. Now assume that $V_{2}=\emptyset$ and $\left|V_{1}\right|=3$, where $V_{1}=\{u, v, w\}$. Since $G\left[V_{1}\right]$ has no isolated vertices, $G\left[V_{1}\right] \in\left\{P_{3}, C_{3}\right\}$. Moreover, every vertex in $V_{0}=V \backslash\{u, v, w\}$ must be adjacent to at least two vertices of $V_{1}$. Clearly, if $G_{1}=G\left[V_{1}\right]$ and $G_{2}=G\left[V_{0}\right]$, then $G$ is an ntc graph as described in the statement.

Theorem 17. Let $G$ be an ntc graph of order $n$. Then $\gamma_{t R 2}(G)=n$ if and only if $G \in\left\{K_{2}, K_{1,2}\right\}$ or every vertex of $G$ is either a leaf or a weak support vertex.

Proof. Assume that $\gamma_{t R 2}(G)=n$. Clearly, if $n \in\{2,3\}$, then $G \in\left\{K_{2}, K_{1,2}\right\}$. Hence assume that $n \geq 4$. Suppose first that $G$ has a vertex $w$ which is neither a leaf nor a support vertex. Define the function $f$ by $f(w)=0$ and $f(x)=1$ for all $x \in V(G) \backslash\{w\}$. Clearly $f$ is a TR2DF on $G$ with weight $n-1$, a contradiction. Thus, each vertex of $G$ is either a leaf or a support vertex. Now suppose that $G$ has a strong support vertex, say $u$. Let $u_{1}$ and $u_{2}$ be two leaves adjacent to $u$. Define the function $f$ by $f(u)=2, f\left(u_{1}\right)=f\left(u_{2}\right)=0$ and $f(x)=1$ otherwise. Since $n \geq 4, f$ is clearly a TR2DF on $G$ of weight $n-1$, a contradiction too. Therefore, every vertex of $G$ is either a leaf or a weak support vertex as desired. The converse is obvious.

## 5. Bounds

We present in this section some bounds on the total Roman $\{2\}$-domination number of ntc graphs in terms of the order, maximum and minimum degrees.

Proposition 18. Let $G$ be an ntc graph of order $n$ with girth $g \geq 6$ and minimum degree $\delta \geq 2$. Then $\gamma_{t R 2}(G) \leq n+2-(\Delta+\delta)$.

Proof. Let $u$ be a vertex of $G$ of maximum degree and let $v$ be any neighbour of $u$. Define the function $f$ on $V(G)$ by $f(u)=1, f(v)=1, f(w)=0$ for all $w \in N(\{u, v\}) \backslash\{u, v\}$ and $f(w)=1$ otherwise. Since since $\delta \geq 2$ and $g \geq 6$,
set $A=V(G) \backslash N[\{u, v\}]$ is non-empty and no vertex of $A$ has two neighbors $N[\{u, v\}]$. Hence $f$ is well defined and is a TR2DF of weight $2+n-\left(\Delta+\operatorname{deg}_{G}(v)\right)$, and thus

$$
\gamma_{t R 2}(G) \leq 2+n-\left(\Delta+\operatorname{deg}_{G}(v)\right) \leq n+2-(\Delta+\delta)
$$

The sharpness of the previous bound can be seen by considering the cycles $C_{6}$ and $C_{7}$. Moreover, to see that the condition $\delta \geq 2$ is essential in the statement of Proposition 18, consider the star $K_{1, n-1}$ with $n \geq 3$, where $\gamma_{t R 2}\left(K_{1, n-1}\right)=$ $3>n+2-(\Delta+\delta)=2$.

Corollary 19. Let $G$ be an ntc graph of order $n$ with girth $g \geq 6$ and minimum degree $\delta \geq 2$ such that $\gamma_{t R 2}(G)=n+2-(\Delta+\delta)$. Then for every vertex $u$ of maximum degree we have that $d(v)=\delta(G)$ for all $v \in N(u)$.

Proposition 20. Let $G$ be an ntc graph. Then

$$
\gamma_{t R 2}(G) \geq\left\lceil\frac{2 n}{\Delta+1}\right\rceil
$$

If $\gamma_{t R 2}(G)=\frac{2 n}{\Delta+1}$, then $V_{2}=\emptyset$ for all $\gamma_{t R 2}(G)$-function $f=\left(V_{0}, V_{1}, V_{2}\right)$.
Proof. Let $f=\left(V_{0}, V_{1}, V_{2}\right)$ be a $\gamma_{t R 2}(G)$-function and let us denote by $V_{02}=$ $\left\{w \in V_{0}: N(w) \cap V_{2} \neq \emptyset\right\}$ and by $V_{01}=V_{0} \backslash V_{02}$. Thus $V(G)=V_{01} \cup V_{02} \cup V_{1} \cup V_{2}$. Since any vertex $v \in V_{2}$ must have at least one neighbor in $V_{1} \cup V_{2}$, we deduce that for each $v \in V_{2},\left|N(v) \cap V_{02}\right| \leq \Delta-1$ and thus $\left|V_{02}\right| \leq(\Delta-1)\left|V_{2}\right|$. Analogously, $2\left|V_{01}\right| \leq(\Delta-1)\left|V_{1}\right|$, because each vertex in $V_{01}$ must have at least two neighbors in $V_{1}$. Hence

$$
\begin{aligned}
n & =\left|V_{01}\right|+\left|V_{02}\right|+\left|V_{1}\right|+\left|V_{2}\right| \leq \frac{\Delta-1}{2}\left|V_{1}\right|+(\Delta-1)\left|V_{2}\right|+\left|V_{1}\right|+\left|V_{2}\right| \\
& =\frac{\Delta+1}{2}\left|V_{1}\right|+\Delta\left|V_{2}\right| \leq \frac{\Delta+1}{2}\left(\left|V_{1}\right|+2\left|V_{2}\right|\right)=\frac{\Delta+1}{2} \gamma_{t R 2}(G),
\end{aligned}
$$

which leads to the desired result. If $\gamma_{t R 2}(G)=\frac{2 n}{\Delta+1}$, then all the previous inequalities become equalities and hence $\left|V_{2}\right|=0$.

The sharpness of the bound in Proposition 20 can be shown for cycles.

## 6. Total Roman $\{2\}$-Domination of Trees

In this section, we present a lower and upper bounds on the total Roman $\{2\}$ domination number of trees. We start with a simple observation.

Observation 21. Let $G$ be a graph without isolated vertices and $v \in V(G) a$ support vertex of $G$.

- For any total Roman $\{2\}$-dominating function $f$ of $G, f(v) \geq 1$.
- If $v$ is a strong support vertex, then there exists a $\gamma_{t R 2}(G)$-function $f$ such that $f(v)=2$.

Theorem 22. Let $T$ be a tree of order $n \geq 2$ with $\ell(T)$ leaves. Then

$$
\gamma_{t R 2}(T) \geq\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil .
$$

This bound is sharp for paths, stars and double stars.
Proof. The proof is by induction on $n$. Clearly for all nontrivial trees of order $n \leq 4$ we have $\gamma_{t R 2}(T)>\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil$. For the inductive hypothesis, let $n \geq 5$ and assume that for every tree of order at least 2 and less than $n$ the result is true. Let $T$ be a tree of order $n$. If $\operatorname{diam}(T)=2$, then $T$ is a star, which yields $\gamma_{t R 2}(T)=3=\left\lceil\frac{2(n-n+1+3)}{3}\right\rceil$. If $\operatorname{diam}(T)=3$, then $T$ is a double star and we have $\gamma_{t R 2}(T)=4=\left\lceil\frac{2(n-n+2+3)}{3}\right\rceil$. Henceforth we can $\operatorname{assume} \operatorname{diam}(T) \geq 4$. Let $f$ be a $\gamma_{t R 2}(T)$-function.

If $T$ has a strong support vertex $u$ with at least two leaves, say $u_{1}$ and $u_{2}$, then let $T^{\prime}=T-u_{1}$. By Observation 21, $f(u) \geq 1$ and we may assume without loss of generality that $f\left(u_{2}\right) \geq f\left(u_{1}\right)$. Now the function $f$, restricted to $T^{\prime}$ is a TR2DF of $T^{\prime}$ and we deduce from the inductive hypothesis that

$$
\gamma_{t R 2}(T)=\omega(f) \geq \gamma_{t R 2}\left(T^{\prime}\right) \geq\left\lceil\frac{2((n-1)-(\ell(T)-1)+3)}{3}\right\rceil=\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil .
$$

Thus in the sequel, we can assume that $T$ has no strong support vertex. Let $v_{1} v_{2} \cdots v_{k}$ be a diametral path in $T$ and root $T$ in $v_{k}$. Since $T$ has no strong support vertex, any child of $v_{3}$ is a leaf or a support vertex of degree 2 . We consider the following cases.

Case 1. $\operatorname{deg}_{T}\left(v_{3}\right) \geq 3$. First suppose $v_{3}$ is a support vertex. By Observation 21, we may assume $f\left(v_{2}\right)=f\left(v_{3}\right)=2$. Let $T^{\prime}=T-v_{1}$ and define $h: V\left(T^{\prime}\right) \rightarrow$ $\{0,1,2\}$ by $h\left(v_{2}\right)=1$ and $h(x)=f(x)$ for $x \in V\left(T^{\prime}\right) \backslash\left\{v_{2}\right\}$. Clearly $h$ is a TR2DF of $T^{\prime}$. It follows from the induction hypothesis that

$$
\begin{aligned}
\gamma_{t R 2}(T) & =\omega(f)=\omega(h)+1 \geq \gamma_{t R 2}\left(T^{\prime}\right)+1 \\
& \geq\left\lceil\frac{2((n-1)-\ell(T)+3)}{3}\right\rceil+1>\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil,
\end{aligned}
$$

as desired. Now suppose $v_{3}$ is not a support vertex. Assume $u_{2}$ is a child of $v_{3}$ and $u_{1}$ is a leaf adjacent to $u_{2}$. Clearly $f\left(u_{1}\right)+f\left(u_{2}\right) \geq 2$ and $f\left(v_{1}\right)+f\left(v_{2}\right) \geq 2$. Assume without loss of generality that $f\left(v_{2}\right) \geq f\left(u_{2}\right)$. Let $T^{\prime}=T-\left\{u_{1}, u_{2}\right\}$. If
$f\left(v_{3}\right) \geq 1$ or $\operatorname{deg}\left(v_{3}\right) \geq 4$, then clearly the function $f$ restricted to $T^{\prime}$ is a TR2DF of $T$ and we conclude from the inductive hypothesis that

$$
\begin{aligned}
\gamma_{t R 2}(T) & =\omega(f)=\omega\left(\left.f\right|_{T^{\prime}}\right)+2 \geq \gamma_{t R 2}\left(T^{\prime}\right)+2 \\
& \geq\left\lceil\frac{2((n-2)-(\ell(T)-1)+3)}{3}\right\rceil+2>\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil,
\end{aligned}
$$

as desired. Hence assume that $f\left(v_{3}\right)=0$ and $\operatorname{deg}\left(v_{3}\right)=3$. Let $T^{\prime}=T-$ $\left\{u_{1}, u_{2}, v_{1}\right\}$. Then the function $g: V\left(T^{\prime}\right) \rightarrow\{0,1,2\}$ defined by $g\left(v_{3}\right)=1$ and $g(x)=f(x)$ for $x \in V\left(T^{\prime}\right) \backslash\left\{v_{3}\right\}$, is a TR2DF of $T^{\prime}$ of weight $\gamma_{t R 2}(T)-2$. By the inductive hypothesis we have

$$
\begin{aligned}
\gamma_{t R 2}(T) & =\omega(f)=\omega(g)+2 \geq \gamma_{t R 2}\left(T^{\prime}\right)+2 \\
& \geq\left\lceil\frac{2((n-3)-(\ell(T)-1)+3)}{3}\right\rceil+2>\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil .
\end{aligned}
$$

Case 2. $\operatorname{deg}_{T}\left(v_{3}\right)=2$. As above we have $f\left(v_{1}\right)+f\left(v_{2}\right) \geq 2$. If $f\left(v_{3}\right) \geq 1$, then the function $g: V\left(T-v_{1}\right) \rightarrow\{0,1,2\}$ defined by $g\left(v_{2}\right)=1$ and $g(x)=f(x)$ for $x \in V\left(T^{\prime}\right) \backslash\left\{v_{2}\right\}$, is a TR2DF of $T-v_{1}$ of weight $\gamma_{t R 2}(T)-1$ and by the inductive hypothesis we obtain

$$
\begin{aligned}
\gamma_{t R 2}(T) & =\omega(f)=\omega(g)+1 \geq \gamma_{t R 2}\left(T-v_{1}\right)+1 \\
& \geq\left\lceil\frac{2((n-1)-\ell(T)+3)}{3}\right\rceil+1>\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil .
\end{aligned}
$$

Hence let $f\left(v_{3}\right)=0$. If $f\left(v_{1}\right)+f\left(v_{2}\right) \geq 3$, then reassigning $v_{1}, v_{2}, v_{3}$ the value 1 provides a $\gamma_{t R 2}(T)$-function $f^{\prime}$ for which $f^{\prime}\left(v_{3}\right) \geq 1$, and this situation was considered above. Therefore, we can assume that $f\left(v_{1}\right)+f\left(v_{2}\right)=2$. More precisely, $f\left(v_{1}\right)=f\left(v_{2}\right)=1$. It follows that $f\left(v_{4}\right) \geq 1$. Let $T^{\prime}=T-\left\{v_{1}, v_{2}, v_{3}\right\}$. Clearly $T^{\prime}$ is nontrivial since $\operatorname{diam}(T) \geq 4$. Now if $T^{\prime}$ has order 2 , then $T$ is a path $P_{5}$ and $\gamma_{t R 2}\left(P_{5}\right)=4 \geq\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil$. Hence suppose that $T^{\prime}$ has order at least three. Note that $\ell(T)-1 \leq \ell\left(T^{\prime}\right) \leq \ell(T)$. Also, the function $f$ restricted to $T^{\prime}$ is a T2RDF of $T^{\prime}$ of weight $\omega(f)-2$. We deduce from the inductive hypothesis on $T^{\prime}$ that

$$
\begin{aligned}
\gamma_{t R 2}(T) & =\omega(f)=\omega\left(\left.f\right|_{T^{\prime}}\right)+2 \geq \gamma_{t R 2}\left(T^{\prime}\right)+2 \\
& \geq\left\lceil\frac{2((n-3)-\ell(T)+3)}{3}\right\rceil+2 \geq\left\lceil\frac{2(n-\ell(T)+3)}{3}\right\rceil
\end{aligned}
$$

which competes the proof.
Lemma 23. If $T$ is a tree obtained from a path $v_{1} v_{2} \cdots v_{k}(k \geq 4)$ by adding a pendant path $v_{k-1} w$, then $\gamma_{t R 2}(T)<\frac{2(k+3)}{3}$.

Proof. If $k \equiv 0(\bmod 3)$, then define the function $f$ by $f\left(v_{3 i+1}\right)=f\left(v_{3 i+2}\right)=1$ for $0 \leq i \leq \frac{k}{3}-2, f\left(v_{k-2}\right)=1, f\left(v_{k-1}\right)=2$ and $f(v)=0$ for any remaining vertex $v$. If $k \equiv 1(\bmod 3)$, then define the function $f$ by $f\left(v_{3 i+1}\right)=f\left(v_{3 i+2}\right)=1$ for $0 \leq i \leq \frac{k-1}{3}-1, f\left(v_{k-1}\right)=2$ and $f(v)=0$ for any remaining vertex $v$. If $k \equiv 2(\bmod 3)$, then define the function $f$ by $f\left(v_{3 i+1}\right)=f\left(v_{3 i+2}\right)=1$ for $0 \leq i \leq \frac{k-2}{3}-1, f\left(v_{k-2}\right)=1, f\left(v_{k-1}\right)=2$ and $f(v)=0$ for any remaining vertex $v$. Clearly $f$ is an TR2DF of weight smaller than $\frac{2(k+3)}{3}$.

Theorem 24. For every tree $T$ of order $n(T) \geq 4$ with $s(T)$ support vertices,

$$
\gamma_{t R 2}(T) \leq \frac{3 n(T)+2 s(T)}{4}
$$

with equality if and only if $T$ is the corona of a tree.
Proof. If $T$ is the corona of a tree $T^{\prime}$, then $\gamma_{t R 2}(T)=n(T)=\frac{3 n(T)+2 s(T)}{4}$. To prove that if $T$ is a tree of order $n(T) \geq 4$ with $s(T)$ support vertices, then $\gamma_{t R 2}(T) \leq \frac{3 n(T)+2 s(T)}{4}$ with equality only if $T$ is the corona of a tree, we proceed by induction on the order $n(T)$. If $n(T)=4$, then $T$ is either a star $K_{1,3}$, where $\gamma_{t R 2}\left(K_{1,3}\right)=3<\frac{3 n(T)+2 s(T)}{4}$ or a path $P_{4}$ where $\gamma_{t R 2}\left(P_{4}\right)=4=\frac{3 n(T)+2 s(T)}{4}$ and $P_{4}$ is the corona of the path $P_{2}$. Let $n(T) \geq 5$ and assume that every $T^{\prime}$ of order $n\left(T^{\prime}\right)<n(T)$ with $s\left(T^{\prime}\right)$ support vertices satisfies $\gamma_{t R 2}\left(T^{\prime}\right) \leq \frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}$ with equality only if $T^{\prime}$ is the corona of a tree. Let $T$ be a tree of order $n(T)$. If $T$ is a star, then $\gamma_{t R 2}(T)=3<\frac{3 n(T)+2 s(T)}{4}$. Likewise, if $T$ is a double star, then $\gamma_{t R 2}(T)=4<\frac{3 n(T)+2 s(T)}{4}$ (since $n(T) \geq 5$ ). Henceforth, we can assume that $T$ has diameter at least 4 . Denote by $T_{x}$ the subtree induced by a vertex $x$ and its descendants in the rooted tree $T$.

If $T$ has a strong support vertex $u$ with at least three leaves, then let $T^{\prime}$ be the tree obtained from $T$ by removing a leaf neighbor $w$ of $u$. Let $f$ be a $\gamma_{t R 2}\left(T^{\prime}\right)$ function $f$ such that $f(u)=2, f(v) \geq 1$ for some $v \in N_{T^{\prime}}(u)$. Clearly, $f$ can be extended to TR2D-function of $T$ by assigning a 0 to $w$, and thus $\gamma_{t R 2}(T) \leq$ $\gamma_{t R 2}\left(T^{\prime}\right)$. Now using the induction on $T^{\prime}$ and the fact that $n\left(T^{\prime}\right)=n(T)-1$ and $s\left(T^{\prime}\right)=s(T)$, we obtain the desired result. Henceforth, we can assume that every support vertex of $T$ is adjacent to at most two leaves.

Let $v_{1} v_{2} \cdots v_{k}$ be a diametral path in $T$ such that $\operatorname{deg}_{T}\left(v_{2}\right)$ is as large as possible and root $T$ at $v_{k}$. Clearly $\operatorname{deg}_{T}\left(v_{2}\right) \in\{2,3\}$. We consider the following cases.

Case 1. $\operatorname{deg}_{T}\left(v_{2}\right)=3$. We distinguish the following subcases.
Subcase 1.1. $\operatorname{deg}_{T}\left(v_{3}\right) \geq 3$. If $v_{3}$ is a support vertex or $v_{3}$ has a child with degree 3 other than $v_{2}$, then any $\gamma_{t R 2}\left(T-T_{v_{2}}\right)$-function can be extended to a TR2D-function of $T$ by assigning 2 to $v_{2}$ and 0 to the leaf neighbors of $v_{2}$ and
so $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T-T_{v_{2}}\right)+2$. Since $T-T_{v_{2}}$ is a tree of order at least four, by induction on $T-T_{v_{2}}$ and using the facts $n\left(T-T_{v_{2}}\right)=n(T)-3$ and $s\left(T-T_{v_{2}}\right)=$ $s(T)-1$, we obtain $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+2 \leq \frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2<\frac{3 n(T)+2 s(T)}{4}$. Hence assume that every child of $v_{3}$ except $v_{2}$ is of degree 2 . Let $w_{2}$ be a child of $v_{3}$ besides $v_{2}$ and let $w_{1}$ be the leaf neighbor of $w_{2}$. Clearly any $\gamma_{t R 2}\left(T-T_{w_{2}}\right)$ function can be extended to a TR2D-function of $T$ by assigning 1 to $w_{1}, w_{2}$ and so $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T-T_{w_{2}}\right)+2$. Note that $T-T_{w_{2}}$ is a tree of order at least four with $n\left(T-T_{w_{2}}\right)=n(T)-2$ and $s\left(T-T_{w_{2}}\right)=s(T)-1$. Using the induction on $T-T_{w_{2}}$, we obtain $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+2<\frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2<\frac{3 n(T)+2 s(T)}{4}$.

Subcase 1.2. $\operatorname{deg}_{T}\left(v_{3}\right)=2$ and $\operatorname{deg}_{T}\left(v_{4}\right) \geq 3$. If $T-T_{v_{3}}=P_{3}$, then clearly $\gamma_{t R 2}(T)=5<\frac{(3 n(T)+2 s(T))}{4}$. Hence assume that $T-T_{v_{3}}$ has order at least four. Clearly any $\gamma_{t R 2}\left(T-T_{v_{3}}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 2 to $v_{2}$, a 1 to $v_{1}$ and a 0 to the leaves of $v_{2}$. It follows from the induction hypothesis on $T-T_{v_{3}}$ and the facts $n\left(T-T_{v_{3}}\right)=n-4$ and $s\left(T-T_{v_{3}}\right)=s(T)-1$ that

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T-T_{v_{2}}\right)+3 \leq \frac{3 n\left(T-T_{v_{3}}\right)+2 s\left(T-T_{v_{3}}\right)}{4}+3 \\
& \leq \frac{3(n(T)-4)+2(s(T)-1)}{4}+3<\frac{(3 n(T)+2 s(T))}{4}
\end{aligned}
$$

Subcase 1.3. $\operatorname{deg}_{T}\left(v_{3}\right)=2$ and $\operatorname{deg}_{T}\left(v_{4}\right)=2$. First let $\operatorname{deg}_{T}\left(v_{5}\right) \geq 3$. Hence $T-T_{v_{4}}$ has order at least three. If $T-T_{v_{4}}=P_{3}$, then it is easy to see that $\gamma_{t R 2}(T)=6<\frac{3 n(T)+2 s(T)}{4}$. Thus let $T-T_{v_{4}} \neq P_{3}$. Then any $\gamma_{t R 2}\left(T-T_{v_{4}}\right)$ function can be extended to a TR2D-function of $T$ by assigning a 2 to $v_{2}$ and $v_{3}$, and a 0 to other vertices in $T_{v_{4}}$. Using the induction hypothesis on $T-T_{v_{4}}$ and the facts $n\left(T-T_{v_{4}}\right)=n(T)-5$ and $s\left(T-T_{v_{4}}\right)=s(T)-1$ we obtain

$$
\gamma_{t R 2}(T) \leq \frac{3 n\left(T-T_{v_{4}}\right)+2 s\left(T-T_{v_{4}}\right)}{4}+4<\frac{3 n(T)+2 s(T)}{4} .
$$

Assume now that $\operatorname{deg}_{T}\left(v_{5}\right)=2$. If $\operatorname{deg}\left(v_{i}\right) \leq 2$ for each $i \geq 5$, then the result follows from Lemma 23. Hence let $t$ be the smallest integer such that $\operatorname{deg}\left(v_{t}\right) \geq 3$ for some $t \geq 6$. Let $T^{\prime}=T-T_{v_{t-1}}$. Note that $T^{\prime}$ has order at least three. Suppose that $n\left(T^{\prime}\right)=3$, that is $T^{\prime}=P_{3}$. Then any $\gamma_{t R 2}\left(T_{v_{t-1}}\right)$-function as defined in Lemma 23 can be extended to a TR2DF of $T$ by assigning a 2 to $v_{t}$ and a 0 to other vertices of $T^{\prime}$, and clearly we have $\gamma_{t R 2}(T)<\frac{3 n(T)+2 s(T)}{4}$. Suppose now that $n\left(T^{\prime}\right) \geq 4$. If $t \equiv 1(\bmod 3)$, then any $\gamma_{t R 2}\left(T-T_{v_{t-1}}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 2 to $v_{2}$, a 1 to $v_{3}, v_{3 i+2}, v_{3 i+3}$ for $1 \leq i \leq \frac{t-1}{3}-1$ and a 0 to the remaining vertices of $T_{v_{t-1}}$. Using the induction on $T-T_{v_{t-1}}$ and the fact $\frac{2(t-1)}{3}$ can be rewritten $\frac{3(t-1)}{4}-\frac{t-1}{12}$, we have

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T-T_{v_{t-1}}\right)+\frac{2(t-1)}{3}+1 \\
& \leq \frac{3 n\left(T-T_{v_{4}}\right)+2 s\left(T-T_{v_{4}}\right)}{4}+\frac{3(t-1)}{4}-\frac{t-1}{12}+1 \\
& =\frac{3(n(T)-t)+2(s(T)-1)}{4}+\frac{3(t-1)}{4}-\frac{t-1}{12}+1<\frac{3 n(T)+2 s(T)}{4} .
\end{aligned}
$$

Assume now that $t \equiv 2(\bmod 3)$. Then any $\gamma_{t R 2}\left(T-T_{v_{t-1}}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 2 to $v_{2}$, a 1 to $v_{3 i}, v_{3 i+1}$ for $1 \leq i \leq \frac{t-2}{3}$ and a 0 to the remaining vertices of $T_{v_{t-1}}$. By the induction hypothesis on $T-T_{v_{t-1}}$ we obtain

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T-T_{v_{t-1}}\right)+\frac{2(t-2)}{3}+2 \\
& \leq \frac{3 n\left(T-T_{v_{4}}\right)+2 s\left(T-T_{v_{4}}\right)}{4}+\frac{3(t-2)}{4}-\frac{t-2}{12}+2 \\
& =\frac{3(n(T)-t)+2(s(T)-1)}{4}+\frac{3(t-2)}{4}-\frac{t-2}{12}+2<\frac{3 n(T)+2 s(T)}{4} .
\end{aligned}
$$

Finally, assume that $t \equiv 0(\bmod 3)$. Then any $\gamma_{t R 2}\left(T-T_{v_{t-1}}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 2 to $v_{2}$, a 1 to $v_{3}, v_{3 i+1}, v_{3 i+2}$ for $1 \leq i \leq \frac{t}{3}-1$ and a 0 to the remaining vertices of $T_{v_{t-1}}$. By the induction hypothesis on $T-T_{v_{t-1}}$ we have

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T-T_{v_{t-1}}\right)+\frac{2 t}{3}+1 \\
& \leq \frac{3(n(T)-t)+2(s(T)-1)}{4}+\frac{3 t}{4}-\frac{t}{12}+1 \\
& =\frac{3 n(T)+2 s(T)}{4}+\frac{6-t}{12} \leq \frac{3 n(T)+2 s(T)}{4}
\end{aligned}
$$

If further $\gamma_{t R 2}(T)=\frac{3 n(T)+2 s(T)}{4}$, then we have equality throughout the previous inequality chain. In particular, we have $t=6$ and $\gamma_{t R 2}\left(T-T_{v_{t-1}}\right)=$ $\frac{3(n(T)-t)+2(s(T)-1)}{4}$. It follows from the induction on $T-T_{v_{t-1}}$ that $T-T_{v_{t-1}}$ is the corona of a tree and $v_{6}$ is support vertex (since $\operatorname{deg}_{T}\left(v_{6}\right) \geq 3$ ). It follows that for any $\gamma_{t R 2}\left(T-T_{v_{t-1}}\right)$-function $g, g\left(v_{6}\right) \geq 1$ and clearly $g$ can be extended to a TR2D-function of $T$ by assigning a 2 to $v_{2}$, a 1 to $v_{3}, v_{5}$ and a 0 to other vertices in $T_{v_{5}}$. By the induction hypothesis we obtain $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T-T_{v_{t-1}}\right)+4<$ $\frac{3 n(T)+2 s(T)}{4}$.

Case 2. $\operatorname{deg}_{T}\left(v_{2}\right)=2$. By the choice of the diametral path, we deduce that every child of $v_{3}$ with depth one has degree two. Consider the following subcases.

Subcase 2.1. $\operatorname{deg}_{T}\left(v_{3}\right) \geq 3$. Suppose first that $v_{3}$ is a strong support vertex, and let $u, w$ be two leaves of $v_{3}$. Let $T^{\prime}=T-\left\{u, v_{1}, v_{2}\right\}$. Clearly $T^{\prime}$ is a tree of order $n\left(T^{\prime}\right)=n(T)-3 \geq 4$ with $s\left(T^{\prime}\right)=s(T)-1$ support vertices. Let $g$ be a $\gamma_{t R 2}\left(T^{\prime}\right)$-function. Then we extend $g$ to a TR2D-function of $T$ by assigning a 1 to $v_{1}, v_{2}$ and a 0 to $u$. In addition if $g\left(v_{3}\right) \neq 2$, then we reassign $v_{3}$ and $w$ the values 2 and 0 instead of 1 to both. Now using the induction hypothesis on $T^{\prime}$, we get

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T^{\prime}\right)+2 \leq \frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2 \\
& =\frac{3(n(T)-3)+2(s(T)-1)}{4}+2<\frac{3 n(T)+2 s(T)}{4} .
\end{aligned}
$$

Now, suppose that $v_{3}$ is not support vertex. Recall that every child of $v_{3}$ is a support vertex of degree two. Let $T^{\prime}=T-T_{v_{3}}$. Clearly $T_{v_{3}}$ has order $2 \operatorname{deg}_{T}\left(v_{3}\right)-1$ and $T^{\prime}$ has order $n\left(T^{\prime}\right) \geq 2($ since $\operatorname{diam}(T) \geq 4)$. If $n\left(T^{\prime}\right)=2$, then $\gamma_{t R 2}(T)=2 \operatorname{deg}_{T}\left(v_{3}\right)<\frac{3 n(T)+2 s(T)}{4}$, and if $n\left(T^{\prime}\right)=3$, then $\gamma_{t R 2}(T)=$ $2 \operatorname{deg}_{T}\left(v_{3}\right)+1<\frac{3 n(T)+2 s(T)}{4}$. Hence we assume that $n\left(T^{\prime}\right) \geq 4$, and thus by induction on $T^{\prime}, \gamma_{t R 2}\left(T^{\prime}\right) \leq \frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}$. Since any $\gamma_{t R 2}\left(T^{\prime}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 0 to $v_{3}$ and a 1 to each of the remaining vertices of $T_{v_{3}}, \gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+2\left(\operatorname{deg}_{T}\left(v_{3}\right)-1\right)$. Using the fact that $s\left(T^{\prime}\right) \leq s(T)-\operatorname{deg}_{T}\left(v_{3}\right)+2$, we obtain

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T^{\prime}\right)+2\left(\operatorname{deg}_{T}\left(v_{3}\right)-1\right)=\frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2\left(\operatorname{deg}_{T}\left(v_{3}\right)-1\right) \\
& \leq \frac{3\left(n(T)-2 \operatorname{deg}_{T}\left(v_{3}\right)+1\right)+2\left(s(T)-\operatorname{deg}_{T}\left(v_{3}\right)+2\right)}{4}+2\left(\operatorname{deg}_{T}\left(v_{3}\right)-1\right) \\
& <\frac{3 n(T)+2 s(T)}{4}
\end{aligned}
$$

Next we can assume that $v_{3}$ is a support vertex with $\operatorname{deg}_{T}\left(v_{3}\right)=3$. Let $T^{\prime}=T-\left\{v_{1}, v_{2}\right\}$. As above we can easily see that

$$
\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+2 \leq \frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2 \leq \frac{3 n(T)+2 s(T)}{4} .
$$

If further $\gamma_{t R 2}(T)=\frac{3 n(T)+2 s(T)}{4}$, then we have equality throughout the previous inequality chain. In particular, $\gamma_{t R 2}\left(T-\left\{v_{1}, v_{2}\right\}\right)=\frac{3(n(T)-2)+2(s(T)-1)}{4}$. It follows from the induction on $T-\left\{v_{1}, v_{2}\right\}$ that $T-\left\{v_{1}, v_{2}\right\}$ is the corona of some tree, implying that $T$ is the corona of a tree.

Subcase 2.2. $\operatorname{deg}_{T}\left(v_{3}\right)=2$ and $\operatorname{deg}_{T}\left(v_{4}\right) \geq 3$. If $T^{\prime}=T-T_{v_{3}}=P_{3}$, then clearly $\gamma_{t R 2}(T)=5<\frac{3 n(T)+2 s(T)}{4}$. Hence assume that $T^{\prime} \neq P_{3}$. If $v_{4}$ is support
vertex or has a child with depth 1 and degree at least 3 , then clearly there exists a $\gamma_{t R 2}\left(T^{\prime}\right)$-function that assigns a non-zero positive value to $v_{4}$ and such a $\gamma_{t R 2}\left(T^{\prime}\right)$ function can be extended to a TR2D-function of $T$ by assigning a 1 to $v_{1}, v_{2}$ and a 0 to $v_{3}$. It follows from the induction hypothesis on $T^{\prime}$ that

$$
\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+2 \leq \frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2<\frac{3 n(T)+2 s(T)}{4}
$$

Now let $v_{4}$ have child $w_{2}$ with depth 1 and degree two, and let $w_{1}$ be the leaf neighbor of $w_{2}$. Let $T^{\prime}=T-\left\{w_{2}, w_{1}\right\}$. Clearly, $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+2$. By the inductive hypothesis on $T^{\prime}$ and since $T^{\prime}$ is not a corona, $\gamma_{t R 2}\left(T^{\prime}\right)<\frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}$. Using the facts that $n\left(T^{\prime}\right)=n(T)-2$ and $s\left(T^{\prime}\right)=s(T)-1$ we obtain

$$
\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+2<\frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2 \leq \frac{3 n(T)+2 s(T)}{4}
$$

Henceforth we assume that any child of $v_{4}$ is of depth 2 . Thus $T_{v_{4}}$ is a tree obtain from a star by subdividing every edge twice. Let $w_{1}^{i} w_{2}^{i} w_{3}^{i} v_{4}$ be paths in $T$ where $w_{3}^{i}$ is a child of $v_{4}$ for each $i \in\{1,2, \ldots, t\}$ and $w_{3}^{1}=v_{3}$. If $t \geq 3$, then any $\gamma_{t R 2}\left(T-T_{v_{4}}\right)$-function can be extended to a TR2D-function of $T$ by assigning 1 to $v_{1}, v_{2}, v_{3}, v_{4}, w_{2}^{i}, w_{1}^{i}$ for $i \geq 2$. Now we deduce from the induction hypothesis on $T^{\prime}$ and the facts $n\left(T^{\prime}\right)=n(T)-3 t-1$ and $s\left(T^{\prime}\right) \leq s(T)-t+1$ that

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T^{\prime}\right)+2 t+2 \leq \frac{3(n(T)-3 t-1)+2(s(T)-t+1)}{4} \\
& +2 t+2<\frac{3 n(T)+2 s(T)}{4}
\end{aligned}
$$

Hence assume that $t=2$. If $\operatorname{deg}\left(v_{5}\right) \geq 3$, then let $T^{\prime}=T-T_{v_{4}}$. Then $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T-T_{v_{4}}\right)+6$. By the induction hypothesis on $T^{\prime}$ and the facts $n\left(T-T_{v_{4}}\right)=n(T)-7$ and $s\left(T-T_{v_{4}}\right)=s(T)-2$ we obtain

$$
\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+6 \leq \frac{3(n(T)-7)+2(s(T)-2)}{4}+6<\frac{3 n(T)+2 s(T)}{4}
$$

Thus let $\operatorname{deg}\left(v_{5}\right)=2$ and let $T^{\prime}=T-T_{v_{5}}$. Note that $T^{\prime}$ has order $n\left(T^{\prime}\right) \geq 2$. If $n\left(T^{\prime}\right) \in\{2,3\}$, then one can check that $\gamma_{t R 2}(T)<\frac{3 n(T)+2 s(T)}{4}$. Hence we assume that $n\left(T^{\prime}\right) \geq 4$. Then $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+6$. It follows from the induction hypothesis on $T-T_{v_{5}}$ and the facts $n\left(T^{\prime}\right)=n(T)-8$ and $s\left(T^{\prime}\right) \leq s(T)-1$ that

$$
\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+6 \leq \frac{3(n(T)-8)+2(s(T)-1)}{4}+6<\frac{3 n(T)+2 s(T)}{4}
$$

Subcase 2.3. $\operatorname{deg}_{T}\left(v_{3}\right)=\operatorname{deg}\left(v_{4}\right)=2$. First let $\operatorname{deg}_{T}\left(v_{5}\right) \geq 3$. If $T^{\prime}=T-$ $T_{v_{4}}=P_{3}$, then it is easy to see that $\gamma_{t R 2}(T)=5<\frac{3 n(T)+2 s(T)}{4}$. Hence assume that
$T^{\prime} \neq P_{3}$. If $v_{5}$ is a support vertex, then $v_{5}$ is assigned a non-zero positive value under any $\gamma_{t R 2}\left(T^{\prime}\right)$-set and thus one can easily see that $\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T^{\prime}\right)+3$. Using the induction hypothesis on $T^{\prime}$ and the facts $n\left(T^{\prime}\right)=n(T)-4$ and $s\left(T^{\prime}\right)=$ $s(T)-1$ we obtain

$$
\gamma_{t R 2}(T) \leq \frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+3<\frac{3 n(T)+2 s(T)}{4} .
$$

If $v_{5}$ has child $w$ with depth one, then since there is a $\gamma_{t R 2}\left(T-T_{w}\right)$-function that assigns a non-zero positive value to $v_{5}$, such a $\gamma_{t R 2}\left(T-T_{w}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 2 to $w$ and 0 to other vertices in $T_{w}$. By the inductive hypothesis on $T-T_{w}$ and since $T-T_{w}$ is not a corona, $\gamma_{t R 2}\left(T-T_{w}\right)<\frac{3 n\left(T-T_{w}\right)+2 s\left(T-T_{w}\right)}{4}$. Moreover, we have $n\left(T-T_{w}\right) \leq n(T)-2$ and $s\left(T-T_{w}\right)=n(T)-1$, and thus

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T-T_{w}\right)+2<\frac{3 n\left(T-T_{w}\right)+2 s\left(T-T_{w}\right)}{4}+2 \\
& \leq \frac{3(n(T)-2)+2(s(T)-1)}{4}+2=\frac{3 n(T)+2 s(T)}{4}
\end{aligned}
$$

Suppose now that $v_{5}$ has child $w$ with depth two. Let $w$ have $t_{3}$ leaves, $t_{2}$ children with depth one and degree at least three and $t_{1}$ children with depth one and degree two. Let $T^{\prime}=T-T_{w}$. Then any $\gamma_{t R 2}\left(T^{\prime}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 2 to every child of $w$ with depth one, $1+t$ to $w$ and 0 to other vertices in $T_{w}$, where $t=0$ if $t_{3}=0$ and $t=1$ if $t_{3} \geq 1$. Clearly by the inductive hypothesis on $T^{\prime}$ and since $T^{\prime}$ is not a corona, $\gamma_{t R 2}\left(T^{\prime}\right)<\frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}$. Moreover, we know that $n\left(T^{\prime}\right) \leq n(T)-3 t_{2}-2 t_{1}-t_{3}-1$ and $s\left(T^{\prime}\right)=s(T)-t_{1}-t_{2}-t$. Now

- Assume that $t_{2} \neq 0$ or $t_{3} \neq 0$. Then we have

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T^{\prime}\right)+2 t_{2}+2 t_{1}+1+t<\frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2 t_{2}+2 t_{1}+1+t \\
& \leq \frac{3\left(n(T)-3 t_{2}-2 t_{1}-t_{3}-1\right)+2\left(s(T)-t_{1}-t_{2}-t\right)}{4}+2 t_{2}+2 t_{1}+1+t \\
& \leq \frac{3 n(T)+2 s(T)}{4}
\end{aligned}
$$

- Assume that $t_{2}=0$ and $t_{3}=0$. Thus $t_{3} \geq 1$. Using the fact that there is a $\gamma_{t R 2}\left(T^{\prime}\right)$-function that assigns a non-zero positive value to $v_{5}$, clearly then such a $\gamma_{t R 2}\left(T^{\prime}\right)$-function can be extended to a TR2D-function of $T$ by assigning a 0 to $w$ and 1 to the remaining vertices of $T_{w}$. It follows that

$$
\begin{aligned}
\gamma_{t R 2}(T) & \leq \gamma_{t R 2}\left(T^{\prime}\right)+2 t_{1}<\frac{3 n\left(T^{\prime}\right)+2 s\left(T^{\prime}\right)}{4}+2 t_{1} \\
& \leq \frac{3\left(n(T)-2 t_{1}-1\right)+2\left(s(T)-t_{1}\right)}{4}+2 t_{1}<\frac{3 n(T)+2 s(T)}{4} .
\end{aligned}
$$

Assume that $v_{5}$ has child with depth three and let $w_{1} w_{2} w_{3} w_{4} v_{5}$ be a path in $T$ where $w_{4}$ is a child of $v_{5}$ different from $v_{4}$. Considering the above cases and subcases we may assume that $\operatorname{deg}\left(w_{i}\right)=2$ for $i \in\{1,2,3,4\}$. Clearly $T-T_{w_{4}}$ has a $\gamma_{t R 2}\left(T-T_{w_{4}}\right)$-function $f$ such that $f\left(v_{5}\right) \geq 1$, and $f$ can be extended to a TR2D-function of $T$ by assigning a 1 to $w_{3}, w_{2}, w_{1}$ and 0 to $v_{4}$. Using the induction hypothesis on $T-T_{w_{4}}$ we obtain
$\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T-T_{w_{4}}\right)+3<\frac{3 n\left(T-T_{w_{4}}\right)+2 s\left(T-T_{w_{4}}\right)}{4}+3<\frac{3 n(T)+2 s(T)}{4}$.
Finally, assume that $\operatorname{deg}_{T}\left(v_{5}\right)=2$.
Let $f$ be $\gamma_{t R 2}\left(T-T_{v_{3}}\right)$-function such that $f\left(v_{4}\right)$ is as large as possible. It is easy to see that $f\left(v_{4}\right) \geq 1$ and $f$ can be extended to a TR2D-function of $T$ by assigning a 1 to $v_{1}, v_{2}$ and a 0 to $v_{3}$. Using the induction hypothesis on $T-T_{v_{3}}$ we obtain

$$
\gamma_{t R 2}(T) \leq \gamma_{t R 2}\left(T-T_{v_{3}}\right)+2 \leq \frac{3 n\left(T-T_{v_{3}}\right)+2 s(T)}{4}+2<\frac{3 n(T)+2 s(T)}{4}
$$

We conclude this section with two open problems.
Problem 1. Is the problem of deciding whether $\gamma_{t R 2}(G)=3 \gamma(G)$ for a given graph $G$ NP-hard.

Problem 2. Characterize all graphs $G$ such that $\gamma_{t R 2}(G)=3 \gamma(G)$.

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